LIGRIP H120

Rotating Handheld SLAM LiDAR System



LiGrip handheld rotating laser scanner is a new series of products launched by GreenValley International. The product adopts a simple style design, compact body, light hand-held, convenient operation and flexible installation; with a variety of sensors, it can quickly capture a wide range of scenes Data; supports multi-platform and multi-mode operations, and combines lidar and SLAM algorithms to achieve integrated indoor multi-scene measurement. With GreenValley's self-developed LiFuser-BP point cloud processing software, the point cloud data can be post-processed quickly.

Advantages



Lightweight

Minimalistic design with an Aluminum shell provides a light yet sturdy handheld system



Customizable

Highly adaptable design, allowing for various modular integrations and custom to the users' needs



Versatile

With add-on options allowing for adaptations as a UAV, Vehicle, or Backpack mount, the LiGrip is GreenValley's most versatile LiDAR system to date



Multi-platform

Supports handheld, backpack, vehicle, airborne, and other operating platforms to achieve full coverage of collection requirements in different scenarios and further improving operation efficiency



Multi-modal

Supports two operating modes: mobile WIFI (all-in-one kit) and clientless (pure hand-held built-in) operation, which can be exibly selected according to the operating environment



Cutting-edge SLAM Algorithm

Utilizing GreenValley's very own Industry-leading SLAM (Simutaneous Localization And Mapping) algorithm, LiGrip provides real-time on-the-go accurate positioning as you map your environments

Specifications

| System Parameters | | | |
|-----------------------|----------------------------------|-------------------|-------------------|
| Size | L204mm×W130mm×H385mm | Weight | 1.74kg |
| Battery Pack Size | L134mm×W64.6mm×H167mm | Voltage | 15.2V |
| Battery | 5870mAh | IP Code | IP54 |
| Storage | 256GB SSD | Voltage | USB, Ethernet |
| Suitable Environments | Indoor and outdoor scenarios | Battery Life | ~4h (per battery) |
| LiDAR Parameters | | | |
| Scan Rate | 320,000pts/s | Scan Range | 120m |
| LiDAR Accuracy | ±3cm | FOV° | 280°×360° |
| Camera | | | |
| Camera Type | 360° panoramic lens intergration | Photo resolution | 6080×3040 (2: 1) |
| Data Format | insv | Video resolution | 5760×2880@30fps |
| Video coding | H.264 / H.265 | Size | 72mm×48mm×43mm |
| Resulting Data | | | |
| Relative Accuracy | ≤3cm* | Absolute Accuracy | 5cm |
| Point Cloud Formats | Las, Ply, LiData | | |

Application











